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19th International Conference, ICONIP 2012
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Volume Editors

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Preface

This volume is part of the five-volume proceedings of the 19th International Conference on Neural Information Processing (ICONIP 2012), which was held in Doha, Qatar, during November 12–15, 2012. ICONIP is the annual conference of the Asia Pacific Neural Network Assembly (APNNA). This series of conferences has been held annually since 1994 and has become one of the premier international conferences in the areas of neural networks.

Over the past few decades, the neural information processing community has witnessed tremendous efforts and developments from all aspects of neural information processing research. These include theoretical foundations, architectures and network organizations, modeling and simulation, empirical study, as well as a wide range of applications across different domains. Recent developments in science and technology, including neuroscience, computer science, cognitive science, nano-technologies, and engineering design, among others, have provided significant new understandings and technological solutions to move neural information processing research toward the development of complex, large-scale, and networked brain-like intelligent systems. This long-term goal can only be achieved with continuous efforts from the community to seriously investigate different issues of the neural information processing and related fields. To this end, ICONIP 2012 provided a powerful platform for the community to share their latest research results, to discuss critical future research directions, to stimulate innovative research ideas, as well as to facilitate multidisciplinary collaborations worldwide.

ICONIP 2012 received tremendous submissions authored by scholars coming from 60 countries and regions across six continents. Based on a rigorous peer-review process, where each submission was evaluated by at least two reviewers, about 400 high-quality papers were selected for publication in the prestigious series of *Lecture Notes in Computer Science*. These papers cover all major topics of theoretical research, empirical study, and applications of neural information processing research. In addition to the contributed papers, the ICONIP 2012 technical program included 14 keynote and plenary speeches by Majid Ahmadi (University of Windsor, Canada), Shun-ichi Amari (RIKEN Brain Science Institute, Japan), Guanrong Chen (City University of Hong Kong, Hong Kong), Leon Chua (University of California at Berkeley, USA), Robert Desimone (Massachusetts Institute of Technology, USA), Stephen Grossberg (Boston University, USA), Michael I. Jordan (University of California at Berkeley, USA), Nikola Kasabov (Auckland University of Technology, New Zealand), Juergen Kurths (University of Potsdam, Germany), Erkki Oja (Aalto University, Finland), Marios M. Polycarpou (University of Cyprus, Cyprus), Leszek Rutkowski (Technical University of Czestochowa, Poland), Ron Sun (Rensselaer Polytechnic Institute, USA), and Jun Wang (Chinese University of Hong Kong, Hong Kong). The

ICONIP technical program included two panels. One was on “Challenges and Promises in Computational Intelligence” with panelists: Shun-ichi Amari, Leon Chua, Robert Desimone, Stephen Grossberg and Michael I. Jordan; the other one was on “How to Write Better Technical Papers for International Journals in Computational Intelligence” with panelists: Derong Liu (University of Illinois of Chicago, USA), Michel Verleysen (Université catholique de Louvain, Belgium), Deliang Wang (Ohio State University, USA), and Xin Yao (University of Birmingham, UK). The ICONIP 2012 technical program was enriched by 16 special sessions and “The 5th International Workshop on Data Mining and Cybersecurity.” We highly appreciate all the organizers of special sessions and workshop for their tremendous efforts and strong support.

Our conference would not have been successful without the generous patronage of our sponsors. We are most grateful to our platinum sponsor: *United Development Company PSC (UDC)*; gold sponsors: *Qatar Petrochemical Company, ExxonMobil* and *Qatar Petroleum*; organizers/sponsors: *Texas A&M University at Qatar* and *Asia Pacific Neural Network Assembly*. We would also like to express our sincere thanks to the IEEE Computational Intelligence Society, International Neural Network Society, European Neural Network Society, and Japanese Neural Network Society for technical sponsorship.

We would also like to sincerely thank Honorary Conference Chair Mark Weichold, Honorary Chair of the Advisory Committee Shun-ichi Amari, the members of the Advisory Committee, the APNNA Governing Board and past presidents for their guidance, the Organizing Chairs Rudolph Lorentz and Khalid Qaraqe, the members of the Organizing Committee, Special Sessions Chairs, Publication Committee and Publicity Chairs, for all their great efforts and time in organizing such an event. We would also like to take this opportunity to express our deepest gratitude to the members of the Program Committee and all reviewers for their professional review of the papers. Their expertise guaranteed the high quality of the technical program of the ICONIP 2012!

We would like to express our special thanks to Web manager Wenwen Shen for her tremendous efforts in maintaining the conference website, the publication team including Gang Bao, Huanqiong Chen, Ling Chen, Dai Yu, Xing He, Junjian Huang, Chaobei Li, Cheng Lian, Jiangtao Qi, Wenwen Shen, Shiping Wen, Ailong Wu, Jian Xiao, Wei Yao, and Wei Zhang for spending much time to check the accepted papers, and the logistics team including Hala El-Dakak, Rob Hinton, Geeta Megchiani, Carol Nader, and Susan Rozario for their strong support in many aspects of the local logistics.

Furthermore, we would also like to thank Springer for publishing the proceedings in the prestigious series of *Lecture Notes in Computer Science*. We would, moreover, like to express our heartfelt appreciation to the keynote, plenary, panel, and invited speakers for their vision and discussions on the latest

research developments in the field as well as critical future research directions, opportunities, and challenges. Finally, we would like to thank all the speakers, authors, and participants for their great contribution and support that made ICONIP 2012 a huge success.

November 2012

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Extension of Incremental Linear Discriminant Analysis to Online Feature Extraction under Nonstationary Environments

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Abstract. In this paper, a new approach to an online feature extraction under nonstationary environments is proposed by extending Incremental Linear Discriminant Analysis (ILDA). The extended ILDA not only detect so-called “concept drifts” but also transfer the knowledge on discriminant feature spaces of the past concepts to construct good feature spaces. The performance of the extended ILDA is evaluated for the benchmark datasets including sudden changes and reoccurrence in concepts.

Keywords: incremental learning, concept drift, online feature extraction, linear discriminant analysis, knowledge transfer.

1 Introduction

Recently, online incremental learning becomes popular and increasingly important due to the wide range of online applications such as person identification and pattern recognition [1,2]. However, in the real world, the learning is often enforced under nonstationary environments where a target function or a class boundary changes over time, resulting in increasing loss of relevance between the current and the previous concepts. This leads to the need of model changes to adapt to the current concept promptly [3]. This dynamic nature in actual environments is called “concept drifts” [3]. And it is expected that the performance of the current model would be seriously dropped unless the model has ability to detect the concept drift and to update itself by adapting to changing environments.

Previous types of incremental feature extraction such as Incremental Principal Component Analysis (IPCA) [1] and Incremental Linear Discriminant Analysis (ILDA) [2,4] do not provide this ability. However, we believe that the detection of concept drifts for the feature extraction purposes also plays an important role to enhance the system performance. In order to extract good features under

nonstationary environments, this paper proposes an extended version of ILDA in which it can detect the changes in class boundaries as well as perform the knowledge transfer by utilizing useful discriminant vectors of the past concepts.

In order to find useful features autonomously in different concepts, we extend the Hisada et al.'s incremental linear discriminant analysis with knowledge transfer [2] which was developed for multi-task learning problems. In the proposed extension of ILDA, a discriminant feature space model is incrementally updated not only by learning the current concept data but also by combining effective discriminant vectors selected from the previous concepts based on the class separability. This selective augmentation of discriminant vectors is called *knowledge transfer of feature subspace*.

This paper is organized as follows. In Section 2, we extend the Hisada et al.'s ILDA with knowledge transfer model for the learning in nonstationary environments. Let us call the extended ILDA as ILDA-KT for the notational convenience. In Section 3, we evaluate the performance of ILDA-KT for the three benchmark datasets. Finally, Section 4 gives our conclusions and future work.

2 Extension of ILDA under Nonstationary Environments

2.1 Incremental Learning of Feature Space

First, let us assume that we have a set of N training data which belong to either of C classes. The set of class c samples is denoted as $\mathbf{X}_c = \{\mathbf{x}_{c1}, \dots, \mathbf{x}_{cn_c}\}$ ($c = 1, \dots, C$), where $\mathbf{x}_{cj} \in \mathcal{R}^n$ is the j th data of class c and n_c is the number of class c data. The whole set of training data is denoted as $\mathbf{X} = \{\mathbf{X}_1, \dots, \mathbf{X}_C\}$. For \mathbf{X} , we can define the following between-class scatter matrix \mathbf{S}_B and within-class scatter matrix \mathbf{S}_W :

$$\mathbf{S}_B \stackrel{\text{def}}{=} \sum_{c=1}^C n_c (\bar{\mathbf{x}}_c - \bar{\mathbf{x}})(\bar{\mathbf{x}}_c - \bar{\mathbf{x}})^T \quad (1)$$

$$\mathbf{S}_W \stackrel{\text{def}}{=} \sum_{c=1}^C \mathbf{V}_c \quad (2)$$

where

$$\mathbf{V}_c = \sum_{j=1}^{n_c} (\mathbf{x}_{cj} - \bar{\mathbf{x}}_c)(\mathbf{x}_{cj} - \bar{\mathbf{x}}_c)^T. \quad (3)$$

Here, $\bar{\mathbf{x}}_c$ and $\bar{\mathbf{x}}$ are the mean vectors of the class c data and that of all data, respectively. In general, up to $(C - 1)$ discriminant vectors are calculated for a C -class recognition problem due to the rank of \mathbf{S}_B . Let us define a set of such discriminant vectors as $\mathbf{W} = \{\mathbf{w}_1, \dots, \mathbf{w}_{C-1}\}$ and call the feature space spanned by \mathbf{W} a *discriminant feature space*. To obtain all the discriminant vectors \mathbf{W} , the following objective function has to be maximized:

$$J(\mathbf{W}) = \text{tr} \left(\mathbf{W}^T \mathbf{S}_W^{-1} \mathbf{S}_B \mathbf{W} \right). \quad (4)$$

It is well known that \mathbf{W} is obtained by solving the following generalized eigenvalue problem:

$$\mathbf{S}_B \mathbf{W} = \mathbf{S}_W \mathbf{W} \mathbf{\Lambda} \tag{5}$$

where $\mathbf{\Lambda}$ is a diagonal matrix whose diagonal element λ_i is the eigenvalue of the i th eigenvector \mathbf{w}_i .

Assume that a new chunk of L training samples \mathbf{Y} are given and the number of classes increases from C to C' ($C \leq C' \leq C + L$). The new training samples are denoted as $\mathbf{Y} = \{\mathbf{Y}_1, \dots, \mathbf{Y}_{C'}\}$ where $\mathbf{Y}_c = \{\mathbf{y}_{c1}, \dots, \mathbf{y}_{cl_c}\}$ ($c = 1, \dots, C'$). Here, \mathbf{y}_{cj} is the j th training sample of class c and l_c is the number of class c samples. Note that $L = \sum_c l_c$. Then, the between-class scatter matrix \mathbf{S}_B and the within-class scatter matrix \mathbf{S}_W are updated by the following equations [4]:

$$\mathbf{S}'_B = \sum_{c=1}^{C'} n'_c (\bar{\mathbf{x}}'_c - \bar{\mathbf{x}}') (\bar{\mathbf{x}}'_c - \bar{\mathbf{x}}')^T \tag{6}$$

$$\mathbf{S}'_W = \sum_{c=1}^{C'} \mathbf{V}'_c \tag{7}$$

where

$$\begin{aligned} \mathbf{V}'_c = & \mathbf{V}_c + \frac{l_c^2}{n_c'^2} (\bar{\mathbf{y}}_c - \bar{\mathbf{x}}_c) (\bar{\mathbf{y}}_c - \bar{\mathbf{x}}_c)^T + \frac{n_c^2}{n_c'^2} \sum_{j=1}^{l_c} (\mathbf{y}_{cj} - \bar{\mathbf{x}}_c) (\mathbf{y}_{cj} - \bar{\mathbf{x}}_c)^T \\ & + \frac{l_c(l_c + 2n_c)}{n_c'^2} \sum_{j=1}^{l_c} (\mathbf{y}_{cj} - \bar{\mathbf{y}}_c) (\mathbf{y}_{cj} - \bar{\mathbf{y}}_c)^T \end{aligned} \tag{8}$$

$$\bar{\mathbf{x}}'_c = \frac{n_c}{n'_c} \bar{\mathbf{x}}_c + \frac{1}{n'_c} \sum_{j=1}^{l_c} \mathbf{y}_{cj} \tag{9}$$

$$\bar{\mathbf{x}}' = \frac{N}{N + L} \sum_{c=1}^{C'} n'_c \bar{\mathbf{x}}'_c \tag{10}$$

and $n'_c = n_c + l_c$ and $n_c = 0$ for $c = C + 1, \dots, C'$.

In the proposed ILDA-KT, an individual discriminant space model for each concept is defined and the models are stored separately in the memory. When a known concept is given, the corresponding discriminant space model is retrieved from the memory and trained with new data incrementally. Let us assume that Z concepts were already trained and the discriminant space models $\Omega^{(z)} = \{\mathbf{S}_B^{(z)}, \mathbf{S}_W^{(z)}, \mathbf{\Lambda}^{(z)}, \mathbf{W}^{(z)}, \{\bar{\mathbf{x}}_c^{(z)}\}_{c=1}^{C^{(z)}}, \{n_c^{(z)}\}_{c=1}^{C^{(z)}}\}$ ($z = 1, \dots, Z$) have been stored in the memory.

If a given chunk of data belongs to a new concept, the number of concept Z is incremented by one (i.e. $Z \leftarrow Z + 1$) and the index of the current concept z' is set to Z . Then, LDA is carried out for the given data $\mathbf{X} = \{\{\mathbf{x}_{cj}\}_{j=1}^{l_c}\}_{c=1}^{C^{(z)}}$ where \mathbf{x}_{cj} is j th data of class c , and the Z th discriminant space model $\Omega^{(Z)}$ is

computed by solving the eigenvalue problem in Eq. (5). On the other hand, if a given chunk of data belongs to the z' th known concept, the discriminant space model $\Omega^{(z')}$ is retrieved from the memory, and ILDA [4] is performed for the given data $\mathbf{Y} = \{\{\mathbf{Y}_{cj}\}_{j=1}^{l_c}\}_{c=1}^{C(z')}$ to update $\Omega^{(z')}$ incrementally.

2.2 Detection of Concept Drifts

When a concept drift happens in a pattern recognition problem, class boundaries are changed and this will lead to the change in a discriminant space model. It implies that a between-class scatter matrix \mathbf{S}_B , a within-class scatter matrix \mathbf{S}_W , and the class c mean vector $\bar{\mathbf{x}}_c$ would be varied significantly by a concept drift. Therefore, to detect the changes in class boundaries, the temporal differences in \mathbf{S}_B , \mathbf{S}_W and $\bar{\mathbf{x}}$ between the current and previous stages should be observed.

The proposed concept drift detection relies on a simple thought. Since at least one of the temporal changes in \mathbf{S}_B , \mathbf{S}_W and $\bar{\mathbf{x}}$ are supposed to be large, an indicator to detect a concept drift is defined by the following time difference:

$$\Delta\Omega(t) = \|\Delta\mathbf{S}_B(t)\|_F + \|\Delta\mathbf{S}_W(t)\|_F + \|\Delta\bar{\mathbf{x}}(t)\|_2 \tag{11}$$

where

$$\Delta\mathbf{S}_B(t) = \mathbf{S}_B(t) - \mathbf{S}_B(t - 1) \tag{12}$$

$$\Delta\mathbf{S}_W(t) = \mathbf{S}_W(t) - \mathbf{S}_W(t - 1) \tag{13}$$

$$\Delta\bar{\mathbf{x}}(t) = \sum_{c=1}^C \{\bar{\mathbf{x}}_c(t) - \bar{\mathbf{x}}_c(t - 1)\}. \tag{14}$$

Here, $\|\cdot\|_F$ and $\|\cdot\|_2$ mean the Frobenius norm and the L_2 norm, respectively.

While no concept drift happens, the time difference $\Delta\Omega(t)$ would be small. On the other hand, when a concept drift happens, it is expected that we observe a big jump in $\Delta\Omega(t)$ from the averaged time difference $\overline{\Delta\Omega}(t - 1)$ for the previous time differences $\Delta\Omega(t')$ ($t' = t - 1, t - 2, \dots$). Based on such a simple thought, we propose the following rule for detecting concept drifts:

[Detection of Concept Drifts]

If $\Delta\Omega(t) > \overline{\Delta\Omega}(t - 1)$, suspect a concept drift and do the followings:

- (1) Set $t' = t$.
- (2) If $\Delta\Omega(t) > \overline{\Delta\Omega}(t' - 1)$ is consecutively satisfied for $t = t' + 1, t' + 2, \dots$, then a concept drift is detected.

Otherwise, perform ILDA and update the average time difference $\overline{\Delta\Omega}(t)$.

Note that there is no threshold value in the proposed concept drift detection algorithm.

2.3 Knowledge Transfer

In order to construct a high-performance discriminant space, useful discriminant vectors are searched for the complementary space of the current discriminant

space, which is spanned by $\mathbf{W}^{(z')} = \{w_1^{(z')}, \dots, w_{C^{(z')}-1}^{(z')}\}$. Here, z' is the index of the current concept. To evaluate the usefulness of discriminant vectors, we adopt the following class separability:

$$J(\mathbf{w}) = \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}}. \quad (15)$$

The selection of useful discriminant vectors is conducted as follows. First, all the discriminant vectors $\mathbf{W}^{(z)}$ ($1 \leq z \leq Z$) of the previous concepts are orthogonalized to the current discriminant space. This can be done by calculating the following residue vectors $\mathbf{W}^{(z)} = \{w_1^{(z)}, \dots, w_{C^{(z)}-1}^{(z)}\}$:

$$\hat{\mathbf{w}}_i^{(z)} = \frac{\hat{\mathbf{w}}_i^{(z')}}{\|\hat{\mathbf{w}}_i^{(z')}\|} \quad (i = 1, \dots, C^{(z)} - 1; z = 1, \dots, Z; z \neq z') \quad (16)$$

where $\hat{\mathbf{w}}_i^{(z')} = \mathbf{w}_i^{(z')} - \mathbf{W}^{(z')} \mathbf{W}^{(z')T} \mathbf{w}_i^{(z')}$. Then, the usefulness of a discriminant vectors $\hat{\mathbf{w}}_i^{(z)}$ is evaluated based on the class separability $J(\hat{\mathbf{w}}_i^{(z)})$ in Eq. (15). If the following condition is satisfied, a discriminant vector $\hat{\mathbf{w}}^{(z)}$ of the z th concept is transferred:

$$J(\hat{\mathbf{w}}_i^{(z)}) > \eta \left\{ \min_k \{J(\mathbf{w}_k^{(z')})\} \right\} \quad (17)$$

where η is a positive constant.

A discriminant vector of the previous concept $\hat{\mathbf{w}}_i^{(z')}$ is transferred only if it increases the total class separability by a certain degree against the lowest class separability for the current discriminant vectors $\hat{\mathbf{w}}^{(z')}$. If the condition in Eq. (17) is satisfied, the i th discriminant vector $\hat{\mathbf{w}}_i^{(z')}$ is transferred to the current concept, and it is added to $\mathbf{W}^{(z')}$ as follows:

$$\mathbf{W}^{(z')'} = [\mathbf{W}^{(z')}, \hat{\mathbf{w}}_i^{(z')}] \quad (18)$$

The knowledge transfer is applied to all discriminant vectors $\hat{\mathbf{w}}_i^{(z)}$ ($i = 1, \dots, C^{(z)} - 1$) of the z th concept, and the same computation is applied to other discriminant vectors of the current concept.

3 Performance Evaluation

To evaluate the performance of ILDA-KT under nonstationary environments, we adopt the SEA data [5], the checkerboard data with pulsing drift rate [6] and the contraceptive data [7]. The information on the three datasets is summarized in Table 1. For the SEA data, 250 training data are given to learn and independent 250 test data are used for evaluation at every learning stage. 50 learning stages are learned for each concept and the number of concepts is 4; thus, the total number of training and test data are 50,000, respectively. For the checkerboard data, 25 training data are given at every learning stage and independent 1,024

Table 1. Evaluated datasets

	#Attrib.	#Class	#Train	#Test
SEA [5]	3	2	50,000	50,000
Checkerboard [6]	2	2	10,000	409,600
Contraceptive [7]	9	3	3,315	1,020

Table 2. Accuracies of concept drift detection

	SEA	Checkerboard	Contraceptive
Accuracies	100% (3/3)	100% (3/3)	100%(2/2)

Table 3. Recognition accuracies [%] with standard deviation for SEA, checkerboard and contraceptive data

	SEA	Checkerboard	Contraceptive
ILDA	97.0±0.1	65.1±1.9	40.9±1.1
ILDA-CD	97.0±0.3	68.5±6.0	41.8±0.7
ILDA-KT	97.0±0.2	72.3±3.5	42.1±1.3

test data are used for evaluation. There are two concept to be learned and each concept consists of 200 learning stages; thus, the total number of training and test data are 10,000 and 409,600, respectively. Besides, for the contraceptive data, the use of the dataset is different from the explanation in [7]. 13 data are given as training data and evaluated with 4 data at every learning stage. There are 85 learning stages for each concept and the number of concepts is three; thus, the total number of training and test data are 3,315 and 1,020, respectively.

To see the effectiveness of ILDA-KT as feature extraction, we compare ILDA-KT with the following two models: ILDA and ILDA with concept drift detection function (ILDA-CD). ILDA does not have neither the concept drift detection function nor the knowledge transfer function, while ILDA-CD has only the concept drift detection function. In the experiment, the parameter η in Eq. (17) is set to 0.01.

As seen in Table 2, the drift points are correctly detected for all datasets; thus, the detection of concept drifts works well in ILDA-KT. Table 3 shows the recognition accuracies which are averaged over 50 trials (i.e., the average performance for 50 different data sequences). Note that the recognition accuracy and the number of discriminant vectors are averaged over the entire learning stages. From Table 3, we can see that there is no significant difference in accuracy among three models for the SEA data. This is because no useful discriminant vector exists in other concepts and the knowledge transfer was not carried out in ILDA-KT. On the other hand, ILDA-KT outperforms both ILDA and ILDA-CD in terms of the recognition accuracy for the checkerboard and contraceptive data. Since the checkerboard data are generated under a cyclical environment, this result indicates that the proposed ILDA-KT works well even in the cyclical environments. For both datasets, the accuracy of ILDA-KT is significantly

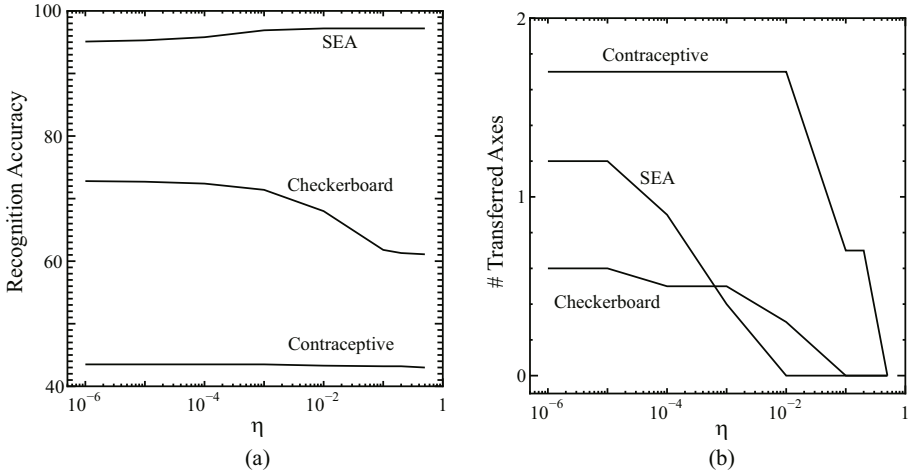


Fig. 1. Influence of η on (a) the recognition accuracy [%] and (b) the number of transferred axes for the SEA, checkerboard and contraceptive data

improved not only by detecting concept drifts correctly but also by transferring useful discriminant vectors as inductive bias. Therefore, we can say that the class separability in Eq. (15) works well as a criterion for knowledge transfer.

Apart from that, the performance of ILDA-CD is better than ILDA for both datasets. Since ILDA-CD does not have any knowledge transfer mechanism (i.e., no inductive bias is available), the discriminant space for a new concept should be learned from scratch after a concept drift is detected. On the other hand, ILDA has neither concept drift detection nor knowledge transfer. Therefore, the discriminant space model is always updated in ILDA without recognizing concepts themselves, but we can consider it as another type of knowledge transfer because the discriminant space model of the previous concept works as inductive bias when learning a new concept. However, there is no guarantee that such inductive bias contributes to the performance enhancement, instead it may lead to giving negative effects (i.e., negative bias). Therefore, we can say that the performance advantage in the proposed ILDA-KT comes from the selective knowledge transfer of useful discriminant vectors.

To see the effect of knowledge transfer in ILDA-KT, the recognition accuracies and the number of discriminant axes are evaluated for different η s. As seen in Figure 1, although the number of transferred discriminant axes are increased, the accuracy for the SEA data is rather dropped if η is smaller than 0.001. This is because the discriminant vectors to be transferred serve as negative bias, leading to the degradation in accuracy.

For the checkerboard data, even if η becomes smaller than 0.001, the number of transferred axes does not change very much; thus, it leads to almost the same recognition accuracy. On the other hand, the accuracies for the contraceptive data are almost the same for any η . This implies that the relatedness among all the concepts are small and the transferred discriminant axes do not contribute to

the performance enhancement. From Table 3, however, we can see that ILDA-KT outperforms ILDA in accuracy, in which only one discriminant space is incrementally updated. Therefore, it suggests that although the usefulness of the knowledge transfer depends on datasets, the performance is not degraded in ILDA-KT by transferring *non-negative bias*.

4 Conclusions and Future Work

In this paper, we propose an extended ILDA with the knowledge transfer function (noted as ILDA-KT). ILDA-KT learns discriminant space models incrementally under nonstationary environments. In addition, the proposed ILDA-KT can detect the changes in concepts to be learned as well as perform the knowledge transfer of effective discriminant vectors from different concepts in order to earn good generalization performance with less training data. From the experiment results, we conclude that the concept drift detection and the knowledge transfer in ILDA-KT work well. However, the usefulness of knowledge transfer depends on datasets.

There still remains future work for this research. The most problematic issue is how to select the parameter η under incremental learning settings. This can be done by using the cross validation if a sufficient number of initial training data are available [8]. However, it is not always ensured that sufficient data are available in real cases. This issue is left as our future work.

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