GENERAL TIMETABLELING SYSTEM FOR SCHOOL

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This project is submitted in partial fulfillment of the requirements for the degree of Bachelor of Education with Honours (Information Technology)

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DECLARATION

No portion of the work referred to in this report has been submitted in support of an application for another degree or qualification of this or any other university or institution of higher learning.

..........................

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The General Timetabling System for School is developed based on the local school timetable structure. The system is implemented using a heuristic generic algorithm that best fit to the timetabling solution. The system is designed on the principle of providing a user-friendly interface for the beginner to learn and use the system with ease. Result of the system testing shown that the system development objectives are successfully achieved. However, there are some limitations on the programming language and database management basis that are still looking for better solution. Additionally, possible future works to improve the usability of the system had also been identified and discussed.
ABSTRAK

CHAPTER 1 INTRODUCTION

1.1 Overview

The General Timetabling System for School (GTSS) refers to a computer generated timetabling system that best suits to most of the schools’ timetable structure in Malaysia, especially within or nearby Kuching. The system requests a complex algorithm to organize, arrange and generate the timetable, as well as a simplest interface for the inputs and outputs. Hence, the timetabling problems could not be solved easily (Causmaecker, P. D., Demeester, P. & Vanden B. G., 2002).

Recently, a survey on the timetabling system of some schools in Kuching area has been carried out. Schools like Sekolah Jenis Kebangsaan Tapah, Sekolah Kebangsaan Siburan, Sekolah Jenis Kebangsaan Beratok are still using the manual system to arrange and manage the timetable for the lessons. This involves a lot of workloads, efforts and skills to produce a satisfactory timetable. Therefore, a Timetabling Committee consists of two to three teachers is established to generate the timetable and manage the sit-in teachers for who cannot conduct their classes along the school days.

There are some computer generated timetabling systems in the market. However, locally developed timetabling systems are limited and the foreign timetabling systems typically do not meet the requirements of local schools. The study and implementation of this system is hopefully assisting the teachers to produce the timetable in an easier, faster, more efficient and effective manner. Eventually the teachers have more time on their lesson plan which is more valuable to the students.
As a general timetabling system, the proposed system will be developed to suit to the timetable structure of local schools. Since there is limitation on user involvement and time constraint, the desired system will focus on the requirements of a few chosen schools in Kuching, Sarawak. The timetabling structures in most local schools are similar. Instead of handling a huge research for all schools, it is better to conduct a smaller, but approachable and deeper research on the representative group.

Basically, the focus is on the features of inputting data and constraints, generating, viewing and printing the timetable, as well as saving and retrieving the databases.

1.2 Problem Statement

The conventional manual timetabling system requires a lot of manpower, heavy workload and time consuming to arrange the entire variables, especially with increasing constraints. The allocation of the teachers, locations and subjects into the best timeslots is a heuristic task that is difficult to be solved manually. Moreover, the outcome might not satisfy the teachers’ requirement like an equivalent working period on every day and potential of clashing cannot be avoided. Existing autonomous timetabling systems are costly, and the structure of foreign timetabling system might not meet the local schools’ requirements. Therefore, an automated computer generated timetabling system is needed. However, a good timetabling system involves a lot of considerations to meet the demand or requirements of local schools.
1.3 Objectives

The objectives of this project are:

a) To assist the Timetabling Committee to produce the timetable in a faster, easier, more efficient and effective manner,

b) To eliminate clashes on timetable, and

c) To generate the timetable automatically when all data are inputted.

1.4 Proposed System

The proposed General Timetabling System for School (GTSS) is a Java standalone application. The programming language that suggested to be used is Java 2, which can be supported by most of the latest platforms and operating systems. In order to run the application, Java 2 Runtime Environment (J2SE) would be installed into the user's system.

The performance and implementation of the proposed system is based on the following recommended specifications:

a) Processor : Pentium IV 1.7 GHz

b) Operating System : Windows ME/XP

c) Random Access Memory : 128 MB

d) Minimum hard drive space : 500 MB

The desired system is developed using the following software:

a) Java 2 for programming, accessing databases and integrating the entire components.

b) Paint Shop Pro 7.0 for graphical user interface development.

c) Others minor utilities to enhance the representation of the system.
1.5 **Significance of Outcome**

From the aspect of timetable management, this project benefits the entire family in the school. The teachers in Timetabling Committee gain the initial benefits on the automated timetabling system by paying less attention on the given task. The desired system assists the committee to produce a more satisfactory timetable faster, easier and without clashes. In addition, the timetable can be regenerated easily after some changes are made. In this way, the teachers can save plenty of time in managing the timetable and pay more attention on their lesson plans. Indirectly, the students also gain intangible benefits from the more valuable lessons. Consequently, the school principal, teachers, students and parents are satisfied with the performance of the Timetabling Committee.

1.6 **Project Schedule**

The project schedule is shown in the Appendix A.

1.7 **Outline of the Project Report**

Chapter 1 introduces the overall outlook on the development of the General Timetabling System for School, including the problem statement, objectives, proposed system and the significance of outcome.

Chapter 2 is a literature review on some significant knowledge for the development of the desired system. This chapter describes several possible alternatives on the algorithms, programming languages, database models as well as the strengths and weaknesses of the existing system in the market.
Chapter 3 focuses on the methodology that might be applicable to the development of the General Timetabling System for School. Overview on several concurrent development methodologies like Object-oriented System Development Methodology, Structured Systems Analysis and Design Method, Structured Systems Analysis and Design Method and System Development Lifecycle are done. Further study on application of the chosen Waterfall Model has been discussed.

Chapter 4 is a detailed analysis on the desired timetabling system. Exiting timetabling framework has been studied and more specific requirements definition is established. The user requirements are collected and analyzed.

Chapter 5 describes the system design of General Timetabling System for School. In this chapter, the design of the data flow, database and user interface are figured out based on the user requirements.

Chapter 6 focuses on the implementation of the desired system. The implementation procedure, algorithm as well as the limitation for some significant interfaces are described.

Chapter 7 describes the tasks and steps taken to test and evaluate the implemented system. Detected defects, user recommendations as well as the system limitations are discussed in this chapter.
Chapter 8 provides an overview on the achievement of the General Timetabling System for School. Future works that might be possible to improve the timetabling system is discussed as well.

1.8 Conclusion

An automated timetabling system is very useful to teachers as a tool to generate and manage the timetable for their school. It saves a lot of workload and time for timetabling process. It allows the data to be saved, stored, retrieved and reused for the following schooling sessions. Therefore, it is worth to develop and be used widely in all schools.
CHAPTER 2    LITERATURE REVIEW

2.1 Algorithm

2.1.1 Overview

According to Kong, S. C. & Kwok, L. F. (1999), timetabling system involves a heuristic function to increase the scheduling performance, as well as producing a best outcome. Currently, the well known solutions for the timetabling system are Genetic Algorithms and Memetic Algorithms (Mohd. Dain, A. A., Shaari, N. S. Gom, Y. S. & Bacheck, Z. A., 2001). However, Causmaecker, P. D. and his friends introduced the Semantic Web as a solution in the domain of timetabling. Berger, J. & Barkaouia, M. (2002) also introduced a Parallel Hybrid Genetic Algorithm for the vehicle routing problem, which they argues to be faster, more cost-effective and highly competitive than the best-known heuristic routing procedures and solutions. Obviously, researchers are still looking forward to heuristics that are suitable for their particular problems (Causmaecker, P. D., Demeester, P. & Vanden B. G., 2002). On the other hand, there are many solutions for the timetabling system, while each of them has their strengths and weaknesses.

2.1.2 Generic Algorithm

Generic Algorithm (GA) was introduced by John Holland (Aziz M. A., 2002). It utilizes several iterations to choose the best solution from a set of solutions for a problem (Yingsong, Z. & Kiyooka, S., 1999). Tzafestas, S. G. (1999) listed four fundamental different ways of GA compared to normal optimization and search procedures, thus:

a) GAs work with a coding of parameter set; not the parameters themselves,

b) GAs search from a population of points; not a single point,
c) GAs use a payoff (objective function) information; not derivatives or other auxiliary knowledge, and
d) GAs use probabilistic transition rules.

Referring to Lin, L. & Jiang, Y. (n.d.), GA follows six processes:

a) Initialize population
b) Testing if one of the stopping criteria (time, fitness, etc)
c) Selecting best-fitted chromosome
d) Applying the genetic operator (likes crossover, mutation, inversion, and obtain)
e) Recombining the offspring and current population to form a new generation
f) Repeating steps (b) to (e).

A similar working procedure of GA is illustrated in Figure 2-1, which is taken form Aliev, R. A. & Aliev R. R. (2001).

![Figure 2-1 A simple Genetic Algorithm](image)

Comparing both of the procedures, it is clear that the population is iteratively evolving through several processes, until a satisfactory result is met. In other words, from a set of chromosomes (population), the new generations are generated using the crossover and mutation technique. This process is continuous until all of the chromosomes have been best fit to the initial problem. Figure 2-2 illustrates the crossover, mutation and combined effect of genetic operations.

![Genetic Operation: Crossover, Mutation and Combined Effect](image)

**Figure 2-2 Genetic Operation: Crossover, Mutation and Combined**


As shown in the figure, crossover operator evolves the new generation by interchanging genes from two chromosomes, as mutation operator evolves genes in a single chromosome. Both of the operators can happen in the same time, where a combined effect performed.

A bit different from other researches, Lin, L. & Jiang, Y. (n.d.) stated that genetic operations include crossover, mutation, inversion, selection and obtain. The processes of crossover and
mutation are the same as the illustration in Figure 2-2. Inversion operator inverses the sequence of genes placed in the chromosome. Selection refers to the “fitness” and “minimal” selection from several sets, and obtain refers to a selection of the entire set while other sets is not existed. Illustration of inversion, obtain and selection operators are shown in Figure 2-3.

![Figure 2-3 Genetic Operation: Inversion, Obtain and Selection](image)

GA works well for a heuristic function in both unconstrained and constrained optimization problems. Although GA is much slower than a well-behaved objective function, it is widely used to solve heuristic functions such as minimum spanning tree, traveling salesman, reliability optimization, job-shop scheduling, transportation, facility layout design and obstacle location allocation (Yingsong, Z. & Kiyooka, S., 1999).

### 2.1.3 Memetic Algorithm

According to Burke, E. K., Newall, J. P. & Weare, R. F. (1999), Memetic Algorithm was first introduced by Moscato and Norman. Moscato, P. (2002) defines Memetic Algorithm (MA) as “a population-based approach for heuristic search in optimization problems”. It is faster...