

PREDICTIVE MAXIMUM POWER POINT TRACKING (MPPT) ALGORITHM FOR PERMANENT EXCHANGE MEMBRANE FUEL CELL (PEMFC)

Mohd Rizzwan bin Minggu

Bachelor of Engineering

Electrical and Electronics Engineering with Honours

2022

UNIVERSITI MALAYSIA SARAWAK

Grade:

Please tick (√) Final Year Project Report Masters PhD

DECLARATION OF ORIGINAL WORK

This declaration is made on the 2nd day of August 2022.

Student's Declaration:

I, Mohd Rizzwan bin Minggu (64892) from Faculty of Engineering hereby declare that the work entitled Predictive Maximum Power Point Tracking (MPPT) Algorithm for **Permanent Exchange Membrane Fuel Cell (PEMFC)** is my original work. I have not copied from any other students' work or from any other sources except where due reference or acknowledgement is made explicitly in the text, nor has any part been written for me by another person.

Mohd Rizzwan bin Minggu (64892)

2nd August 2022 (Date submitted)

Supervisor's Declaration:

I, Ir. Dr Hazrul bin Mohamed Basri hereby certifies that the work entitled Predictive Maximum Power Point Tracking (MPPT) Algorithm for Permanent Exchange Membrane Fuel Cell (PEMFC) was prepared by the above named student and was submitted to the "FACULTY" as a * partial/full fulfillment for the conferment of Bachelor of Engineering in Electrical and Electronics Engineering with Honours, and the aforementioned work, to the best of my knowledge, is the said student's work.

Received for examination by: Ir. Dr Hazrul bin Mohamed Basri

Ir. Dr Hazrul Bin Mohamed Basri Senior Lecturer Faculty of Engineering Dept. of Electrical and Electronics Engineering UNIVERSITI MALAYSIA SARAWAK Date: 2nd August 2022

I declare that Project/Thesis is classified as (Please tick ($\sqrt{}$)):

RESTRICTED

CONFIDENTIAL (Contains confidential information under the Official Secret Act 1972)* (Contains restricted information as specified by the organisation where research was done)*

\checkmark OPEN ACCESS

Validation of Project/Thesis

I therefore duly affirm with free consent and willingly declare that this said Project/Thesis shall be placed officially in the Centre for Academic Information Services with the abiding interest and rights as follows:

- This Project/Thesis is the sole legal property of Universiti Malaysia Sarawak (UNIMAS).
- The Centre for Academic Information Services has the lawful right to make copies for the purpose of academic and research only and not for other purpose.
- The Centre for Academic Information Services has the lawful right to digitalise the content for the Local Content Database.
- The Centre for Academic Information Services has the lawful right to make copies of the Project/Thesis for academic exchange between Higher Learning Institute.
- No dispute or any claim shall arise from the student itself neither third party on this Project/Thesis once it becomes the sole property of UNIMAS.
- This Project/Thesis or any material, data and information related to it shall not be distributed, published, or disclosed to any party by the student except with UNIMAS permission.

Student signature:

(2nd August 202

Supervisor signature:

(2nd August 2022) Ir. Dr Hazrul Bin Mohamed Basri Senior Lecturer **Faculty of Engineering** Dept. of Electrical and Electronics Engineering

Current Address: Department of Electrical and Electronics Engineering, Faculty of VErgineering, SARAWAK Universiti Malaysia Sarawak (UNIMAS), Jalan Datuk Mohammad Musa, 94300 Kota Samarahan, Sarawak.

Notes: * If the Project/Thesis is **CONFIDENTIAL** or **RESTRICTED**, please attach together as annexure a letter from the organisation with the period and reasons of confidentiality and restriction.

[The instrument is duly prepared by The Centre for Academic Information Services]

PREDICTIVE MAXIMUM POWER POINT TRACKING (MPPT) ALGORITHM FOR PERMANENT EXCHANGE MEMBRANE FUEL CELL (PEMFC)

MOHD RIZZWAN BIN MINGGU

A dissertation submitted in partial fulfilment of the requirement for the degree of Bachelor of Engineering

Electrical and Electronics Engineering with Honours

Faculty of Engineering

Universiti Malaysia Sarawak

ACKNOWLEDGEMENT

First and foremost, I would like to express my heartfelt gratitude to my final year project supervisor, Ir. Dr Hazrul bin Mohamed Basri of Universiti Malaysia Sarawak from Department Electrical and Electronics Engineering for his invaluable advice, patience, continuous support, and guidance throughout completing this project. His immense knowledge, plentiful experience, informative advice, and enthusiasm have encouraged me to make this final year project is a success under his supervision.

Next, I would like to thank my dearest family members especially my parent for their encouragement and unlimited supports in terms of finance and moral whenever I need them the most throughout my undergraduate study.

Apart from that, I would like to thank to my beloved friends who have been with me through my ups and downs during my study. Their advice, sharing, patience, motivation, support, and friendship are highly appreciated.

Besides that, I would like to extent my gratitude to Faculty of Engineering, Universiti Malaysia Sarawak for their full support and guidance in this research.

Lastly, special thanks to all people who have provided me assistance, guidance, and directives whether directly or indirectly in making this project a success. Without all of these, my time in undergraduate study would surely not as bright to experience.

ABSTRACT

Renewable energy is increasingly being used as a backup energy source by a wide range of sectors due to concerns about negative impacts of continuous consumption of fossil fuel. Fuel cell power generation technology is gaining importance in its own right in the current global landscape of electricity generation, distribution, and satisfying consumer demand since it has numerous advantages such as environmentally friendly, high efficiency, noise-free, and safe operation. In this project, a PEMFC has been chosen due to its striking features that is suitable for stationary applications like residential and transportation uses. Generally, the output characteristics of fuel cells are non-linear and influenced by parameters such as the cell temperature, oxygen partial pressure, hydrogen partial pressure, and membrane water content. In each particular condition, there is only one unique operating point for a fuel cell system with the maximum output. Therefore, it is important to find the optimal operating voltage or current of fuel cell systems in order to increase the efficiency of fuel cells. This maximum output can be determined by using MPPT method such as P&O, INC, FLC, PSO, MPC and more. The milestone of this project is to develop a fully functional PEMFC system based on the mathematical modelling presented in the literature with predictive MPPT control. This algorithm is said to be able to enhance the performance of the PEMFC system due to high in stability and low in complexity. This project introduces a PEMFC system with model predictive control (MPC). In this project, a DC-DC boost converter is used to regulate the output voltage of the fuel cell in order to extract the maximum output power where the switch of this boost converter is controlled by the MPC. The focus of this project is to show the power characteristics extracted from the PEMFC system by using predictive control. A comparison of PEMFC performances based on the proposed technique with other existing MPPT algorithms will be done to validate the algorithm performance. As a result, model predictive control (MPC) exhibits the fast tracking of MPP locus, outstanding accuracy, and robustness with respect to environmental changes.

ABSTRAK

Tenaga boleh diperbaharui semakin digunakan sebagai sumber tenaga alternatif oleh pelbagai sektor kerana kebimbangan mengenai impak negatif akibat penggunaan bahan api fosil yang berterusan. Kini teknologi penjanaan kuasa sel bahan api menjadi semakin penting dalam landskap global semasa penjanaan, pengedaran, dan memuaskan permintaan pengguna kerana ia mempunyai banyak kelebihan seperti mesra alam, kecekapan tinggi, bebas bunyi dan operasi yang selamat. Dalam projek ini, PEMFC telah dipilih kerana ciri menariknya yang sesuai untuk aplikasi pegun seperti kegunaan kediaman dan pengangkutan. Secara amnya, ciri keluaran sel bahan api adalah tidak linear dan dipengaruhi oleh parameter seperti suhu sel, tekanan separa oksigen, tekanan separa hidrogen dan kandungan air membran. Dalam setiap keadaan tertentu, hanya terdapat satu titik operasi unik untuk sistem sel bahan api dengan keluaran yang maksimum. Oleh itu, adalah penting untuk mencari voltan atau arus operasi optimum bagi sistem sel bahan api untuk meningkatkan kecekapan sel bahan api. Keluaran maksimum ini boleh ditentukan dengan menggunakan kaedah MPPT seperti P&O, INC, FLC, PSO, MPC dan banyak lagi. Pencapaian projek ini adalah untuk membangunkan sistem PEMFC berfungsi sepenuhnya berdasarkan pemodelan matematik yang dibentangkan dalam literatur dengan kawalan MPPT secara ramalan. Algoritma ini dikatakan mampu untuk meningkatkan prestasi sistem PEMFC kerana kestabilan yang tinggi dan ciri kompleksiti yang rendah. Projek ini memperkenalkan sistem PEMFC dengan model ramalan kawalan (MPC). Dalam projek ini, penukar DC-DC lif digunakan untuk mengawal voltan keluaran sel bahan api untuk mengekstrak keluaran kuasa maksimum di mana suis penukar lif ini dikawal oleh MPC. Fokus projek ini adalah untuk menunjukkan ciri kuasa yang diekstrak daripada sistem PEMFC dengan menggunakan kawalan ramalan. Perbandingan prestasi PEMFC berdasarkan teknik yang dicadangkan dengan algoritma MPPT sedia ada yang lain akan dilakukan untuk mengesahkan prestasi algoritma. Hasilnya, model ramalan kawalan (MPC) menghasilkan penjejakan lokus MPP yang pantas, ketepatan yang cemerlang dan keteguhan pada perubahan persekitaran.

TABLE OF CONTENTS

ACKNOWL	EDGE	MENT	i
ABSTRACT	ſ		ii
ABSTRAK			iii
TABLE OF	CONI	`ENTS	iv
LIST OF TA	ABLES		vii
LIST OF FI	GURE	S	viii
LIST OF SY	MBO	LS	xiii
LIST OF AI	BBREV	/IATIONS	XV
Chapter 1	INTI	RODUCTION	1
	1.1	Background	1
	1.2	Problem Statement	3
	1.3	Objectives	4
	1.4	Project Scope	4
	1.5	Thesis Outline	4
Chapter 2	LITE	ERATURE REVIEW	6
	2.1	Introduction	6
	2.2	Permanent Exchange Membrane Fuel Cell (PEMFC)	6
	2.3	Mathematical Modelling of PEMFC	7
		2.3.1 Polarization Curves	7
		2.3.2 Cell Voltage	8
		2.3.3 Thermodynamic Potential	9
		2.3.4 Activation Voltage	10
		2.3.5 Ohmic Voltage	10
		2.3.6 Concentration Voltage	10
		2.3.7 Model Parameters	11

	2.4	DC-DC Power Converter		12
		2.4.1	2.4.1 Buck Converter	
		2.4.2	Boost Converter	12
		2.4.3	Buck-Boost Converter	13
		2.4.4	DC-DC Converter Analysis	13
	2.5	Maxin	num Power Point Tracking (MPPT)	14
		2.5.1	Perturb and Observe (P&O)	16
		2.5.2	Incremental Conductance (INC)	17
		2.5.3	Fuzzy Logic Control (FLC)	19
		2.5.4	Particle Swarm Optimization (PSO)	20
		2.5.5	Model Predictive Control (MPC)	22
	2.6	Resear	Research Gaps	
	• -	C	mary	
	2.7	Summ	lary	26
Chapter 3	2.7 MET	Summ	LOGY	26 27
Chapter 3	2.7 MET 3.1	Summ HODO	LOGY uction	26 27 27
Chapter 3	2.7MET3.13.2	THODO Introd Propo	LOGY uction sed Approach	26 27 27 27
Chapter 3	 2.7 MET 3.1 3.2 3.3 	THODO Introd Propo Block	LOGY uction sed Approach Diagram	26 27 27 27 27 29
Chapter 3	 2.7 MET 3.1 3.2 3.3 3.4 	THODO Introd Propo Block MATI	LOGY uction sed Approach Diagram LAB/Simulink	26 27 27 27 27 29 29
Chapter 3	 2.7 MET 3.1 3.2 3.3 3.4 3.5 	THODO Introd Propo Block MATI PEMF	LOGY uction sed Approach Diagram LAB/Simulink FC System	26 27 27 27 29 29 29 29
Chapter 3	 2.7 MET 3.1 3.2 3.3 3.4 3.5 	THODO Introd Propos Block MATI PEMF 3.5.1	LOGY uction sed Approach Diagram LAB/Simulink FC System Subsystem Block	26 27 27 27 29 29 29 29 31
Chapter 3	 2.7 MET 3.1 3.2 3.3 3.4 3.5 	THODO Introd Propo Block MATI PEMF 3.5.1 3.5.2	LOGY uction sed Approach Diagram LAB/Simulink FC System Subsystem Block Model Parameters	26 27 27 27 29 29 29 29 31 35
Chapter 3	 2.7 MET 3.1 3.2 3.3 3.4 3.5 3.6 	THODO Introd Propos Block MATI PEMF 3.5.1 3.5.2 DC-D	LOGY uction sed Approach Diagram LAB/Simulink C System Subsystem Block Model Parameters C Boost Converter	26 27 27 27 29 29 29 31 35 36
Chapter 3	 2.7 MET 3.1 3.2 3.3 3.4 3.5 3.6 3.7 	THODO Introd Propos Block MATI PEMF 3.5.1 3.5.2 DC-D Model	LOGY uction sed Approach Diagram LAB/Simulink C System Subsystem Block Model Parameters C Boost Converter	26 27 27 29 29 29 31 35 36 38
Chapter 3	 2.7 MET 3.1 3.2 3.3 3.4 3.5 3.6 3.7 3.8 	THODO Introd Propose Block MATI PEMF 3.5.1 3.5.2 DC-D Model PEMF	LOGY uction sed Approach Diagram LAB/Simulink C System Subsystem Block Model Parameters C Boost Converter Predictive Control	26 27 27 29 29 29 29 31 35 36 38 42
Chapter 3	 2.7 MET 3.1 3.2 3.3 3.4 3.5 3.6 3.7 3.8 3.9 	FHODO Introd Propose Block MATI PEMF 3.5.1 3.5.2 DC-D Model PEMF Summ	LOGY uction sed Approach Diagram LAB/Simulink CC System Subsystem Block Model Parameters C Boost Converter Predictive Control C with Model Predictive Control	26 27 27 29 29 29 31 35 36 38 42 43

Chapter 4	RES	JLTS AND DISCUSSION44			
	4.1	Introd	Introduction		
	4.2	MATI	LAB/Simulink Analysis	44	
	4.3	Simul	ation Results	45	
		4.3.1	Case 1: Normal Operating Condition	46	
		4.3.2	Case 2: Variable Operating Temperature	53	
		4.3.3	Case 3: Variable Membrane Water Content	67	
		4.3.4	Case 4: Variable Operating Temperature and	Membrane	
			Water Content	81	
	4.4	Discu	ssion	95	
	4.5	4.5 Summary		106	
Chapter 5	CON	CLUSI	ON	107	
	5.1	Overa	ll Conclusion	107	
	5.2	Limita	ations and Further Recommendations	108	
REFERENCES			109		
APPENDIX	A			115	
APPENDIX B 12			116		

LIST OF TABLES

Table

Page

1.1	Major types of fuel cells [6], [8]	2
2.1	Model parameters of PEMFC mathematical modelling [4], [33], [35]	11
2.2	Analysis for DC-DC converter when switch is CLOSED and OPEN	13
2.3	Analysis of DC-DC converter for V_o and D	14
2.4	Comparison of different MPPT algorithm	26
3.1	PEMFC model parameters	35
4.1	Steady state analysis of V_{FC} , I_{FC} and P_{FC} under different operating	
	conditions	95
4.2	V_{FC} , I_{FC} and P_{FC} ripples under different operating conditions	102

LIST OF FIGURES

Figure

Page

2.1	Basic structure of PEMFC [26]	6
2.2	Typical fuel cell polarization curve [32]	8
2.3	Equivalent circuit of fuel cell [11]	8
2.4	Buck converter configuration [39]	12
2.5	Boost converter configuration [39]	12
2.6	Buck-boost converter configuration [39]	13
2.7	Fuel cell polarization curves and types of losses [5]	14
2.8	MPPT control methods [42]	15
2.9	P&O algorithm flowchart [5]	16
2.10	INC algorithm flowchart [5]	17
2.11	Intersection of $\frac{dV_{FC}}{dI_{FC}}$ and $\frac{V_{FC}}{I_{FC}}$ at I_{op} [5]	18
2.12	Main stages of FLC system [10]	19
2.13	PSO algorithm flowchart [4] [45]	21
2.14	Basic concept of MPC [48]	22
2.15	MPC scheme for boost converter [48]	23
2.16	MPC technique flowchart [48]	25
3.1	Project flowchart	28
3.2	Block diagram of PEMFC system with Model Predictive Control	29
3.3	Proposed topology for PEMFC system	30
3.4	Subsystem block for thermodynamic potential, E_{Nernst}	31
3.5	Subsystem block for activation voltage, V_{act}	32
3.6	Subsystem block for ohmic voltage, Vohm	33
3.7	Subsystem block for concentrated voltage, V _{con}	34
3.8	Proposed topology for boost converter	36
3.9	Proposed topology for Model Predictive Control	38
3.10	$I_{FC}(k+1)$ block diagram for $S = 0$	39
3.11	$I_{FC}(k+1)$ block diagram for $S = 1$	39
3.12	$V_{FC}(k+1)$ block diagram for $S = 0$	40

3.13	$V_{FC}(k+1)$ block diagram for $S = 1$	40
3.14	$P_{FC}(k+1)$ block diagram for $S = 0$	40
3.15	$P_{FC}(k+1)$ block diagram for $S = 1$	40
3.16	Block diagram for $P_{FC}(k + 1)$ comparison	41
3.17	MPC algorithm flowchart [35]	41
3.18	Proposed topology for PEMFC system with Model Predictive Control	42
4.1	PEMFC with Model Predictive Control	44
4.2	PEMFC system with P&O controller	45
4.3	P&O algorithm block diagram	46
4.4	Parameter under normal operating condition (a) T (b) λ	46
4.5	V_{FC} trajectories under normal operating condition	47
4.6	V_{FC} transient state before achieving steady state (a) MPC (b) P&O	48
4.7	V_{FC} fluctuations under normal operating condition (a) MPC (b) P&O	48
4.8	I_{FC} trajectories under normal operating condition	49
4.9	I_{FC} transient state before achieving steady state (a) MPC (b) P&O	50
4.10	I_{FC} fluctuations under normal operating condition (a) MPC (b) P&O	50
4.11	P_{FC} trajectories under normal operating condition	51
4.12	P_{FC} transient state before achieving steady state (a) MPC (b) P&O	52
4.13	P_{FC} fluctuations under normal operating condition (a) MPC (b) P&O	52
4.14	Operating condition variations over time for Case 2 (a) T (b) λ	53
4.15	V_{FC} trajectories under variation of T	54
4.16	V_{FC} transient state before achieving steady state condition under variation	
	of T (a) MPC (b) P&O	55
4.17	V_{FC} transient state at $t = 1 s$ under variation of T (a) MPC (b) P&O	55
4.18	V_{FC} transient state at $t = 2 s$ under variation of T (a) MPC (b) P&O	56
4.19	V_{FC} fluctuations before $t = 1 s$ (a) MPC (b) P&O	56
4.20	V_{FC} fluctuations before $t = 2 s$ (a) MPC (b) P&O	57
4.21	V_{FC} fluctuations before $t = 3 s$ (a) MPC (b) P&O	57
4.22	I_{FC} trajectories under variation of T	58
4.23	I_{FC} transient state before achieving steady state condition under variation	
	of T (a) MPC (b) P&O	59
4.24	I_{FC} transient state at $t = 1 s$ under variation of T (a) MPC (b) P&O	60
4.25	I_{FC} transient state at $t = 2 s$ under variation of T (a) MPC (b) P&O	60

I_{FC} flu	ctuations before $t = 1 s$ (a) MPC (b) P&O	61
I _{FC} flu	ctuations before $t = 2 s$ (a) MPC (b) P&O	61
I _{FC} flu	ctuations before $t = 3 s$ (a) MPC (b) P&O	62
P_{FC} tra	jectories under variation of T	63
P_{FC} tra	insient state before achieving steady state condition under variation	
of T (a) MPC (b) P&O	64
P_{FC} tra	insient state at $t = 1 s$ under variation of T (a) MPC (b) P&O	64
P_{FC} tra	unsient state at $t = 2 s$ under variation of T (a) MPC (b) P&O	65
P_{FC} flu	ictuations before $t = 1 s$ (a) MPC (b) P&O	65
P_{FC} flu	ictuations before $t = 2 s$ (a) MPC (b) P&O	66
P_{FC} flu	ictuations before $t = 3 s$ (a) MPC (b) P&O	66
Operat	ing condition variations over time for Case 3 (a) T (b) λ	67
V_{FC} tra	jectories under variation of λ	68
V _{FC} tra	insient state before achieving steady state condition under variation	
of λ (a)) MPC (b) P&O	69
V _{FC} tra	insient state at $t = 1 s$ under variation of λ (a) MPC (b) P&O	69
V _{FC} tra	insient state at $t = 2 s$ under variation of λ (a) MPC (b) P&O	70
V_{FC} flu	actuations before $t = 1 s$ (a) MPC (b) P&O	70
V_{FC} flu	actuations before $t = 2 s$ (a) MPC (b) P&O	71
V_{FC} flu	actuations before $t = 3 s$ (a) MPC (b) P&O	71
I _{FC} traj	jectories under variation of λ	72
I_{FC} tran	nsient state before achieving steady state condition under variation	
of λ (a)) MPC (b) P&O	73
I _{FC} tra	nsient state at $t = 1 s$ under variation of λ (a) MPC (b) P&O	74
I_{FC} tran	nsient state at $t = 2 s$ under variation of λ (a) MPC (b) P&O	74
I_{FC} flu	ctuations before $t = 1 s$ (a) MPC (b) P&O	75
I_{FC} flu	ctuations before $t = 2 s$ (a) MPC (b) P&O	75
I _{FC} flu	ctuations before $t = 3 s$ (a) MPC (b) P&O	76
P_{FC} tra	jectories under variation of λ	77
P_{FC} tra	unsient state before achieving steady state condition under variation	
of λ (a)) MPC (b) P&O	78
P_{FC} tra	unsient state at $t = 1 s$ under variation of λ (a) MPC (b) P&O	78
P_{FC} tra	unsient state at $t = 2 s$ under variation of λ (a) MPC (b) P&O	79

4.55	P_{FC} fluctuations before $t = 1 s$ (a) MPC (b) P&O	79
4.56	P_{FC} fluctuations before $t = 2 s$ (a) MPC (b) P&O	80
4.57	P_{FC} fluctuations before $t = 3 s$ (a) MPC (b) P&O	80
4.58	Operating condition variations over time for Case 4 (a) T (b) λ	81
4.59	V_{FC} trajectories under variation of T and λ simultaneously	82
4.60	V_{FC} transient state before achieving steady state condition under variation	
	of <i>T</i> and λ (a) MPC (b) P&O	83
4.61	V_{FC} transient state at $t = 1 s$ under variation of T and λ (a) MPC (b) P&O	83
4.62	V_{FC} transient state at $t = 2 s$ under variation of T and λ (a) MPC (b) P&O	84
4.63	V_{FC} fluctuations before $t = 1 s$ (a) MPC (b) P&O	84
4.64	V_{FC} fluctuations before $t = 2 s$ (a) MPC (b) P&O	85
4.65	V_{FC} fluctuations before $t = 3 s$ (a) MPC (b) P&O	85
4.66	I_{FC} trajectories under variation of T and λ simultaneously	86
4.67	I_{FC} transient state before achieving steady state condition under variation	
	of <i>T</i> and λ (a) MPC (b) P&O	87
4.68	I_{FC} transient state at $t = 1 s$ under variation of T and λ (a) MPC (b) P&O	88
4.69	I_{FC} transient state at $t = 2 s$ under variation of T and λ (a) MPC (b) P&O	88
4.70	I_{FC} fluctuations before $t = 1 s$ (a) MPC (b) P&O	89
4.71	I_{FC} fluctuations before $t = 2 s$ (a) MPC (b) P&O	89
4.72	I_{FC} fluctuations before $t = 3 s$ (a) MPC (b) P&O	90
4.73	P_{FC} trajectories under variation of T and λ simultaneously	91
4.74	P_{FC} transient state before achieving steady state condition under variation	
	of T and λ (a) MPC (b) P&O	92
4.75	P_{FC} transient state at $t = 1 s$ under variation of T and λ (a) MPC (b) P&O	92
4.76	P_{FC} transient state at $t = 2 s$ under variation of T and λ (a) MPC (b) P&O	93
4.77	P_{FC} fluctuations before $t = 1 s$ (a) MPC (b) P&O	93
4.78	P_{FC} fluctuations before $t = 2 s$ (a) MPC (b) P&O	94
4.79	P_{FC} fluctuations before $t = 3 s$ (a) MPC (b) P&O	94
4.80	V-I curve of PEMFC system under normal operating condition	96
4.81	P-I curve of PEMFC system under normal operating condition	96
4.82	P_{H_2} variation over time	97
4.83	P_{O_2} variation over time	97
4.84	P-I curve of PEMFC under different operating temperatures	98

4.85	P-I curve of PEMFC with different amount of membrane water content	99
4.86	Intersection of P-I and V-I curves of PEMFC system	103
4.87	(a) Switching state of MPC technique (b) Zoom from 0.012 s to 0.018 s	104
4.88	(a) Switching state of P&O algorithm (b) Zoom from 0.012 s to 0.018 s	104
4.89	(a) Duty cycle of P&O controller (b) Zoom from 0 s to 0.05 s	105

LIST OF SYMBOLS

ΔI_{FC}	—	Change/ripple in fuel cell current
ΔP_{FC}	_	Change/ripple in fuel cell power
ΔV_{FC}	_	Change/ripple in fuel cell voltage
E _{Nernst}	_	Thermodynamic potential
I _{FC}	_	Fuel cell current
P_{H_2}	_	Partial pressure of hydrogen
P_{O_2}	_	Partial pressure of hydrogen
P_{FC}	—	Fuel cell power
T _{ref}	—	Standard temperature
T_s	—	Sampling time
V_{FC}	—	Fuel cell voltage
V _{act}	_	Activation voltage
V _{cell}	—	Cell voltage
V _{con}	—	Concentration voltage
V _{ohm}	—	Ohmic voltage
k_{H_2}	_	Hydrogen valve molar constant
k_{O_2}	—	The oxygen valve molar constant
k _r	_	Modeling constant
q_{H_2}	_	Molar flow of hydrogen
q_{O_2}	—	Molar flow of oxygen
r_m	—	Membrane specific resistivity
t_m	—	Membrane thickness
v_L	—	Voltage across inductor
ξ_{1-4}	_	Parametric coefficients
$ au_{H_2}$	_	Hydrogen time constant
$ au_{O_2}$	_	Oxygen time constant
Δi_L	—	Change in inductor current
ΔG	—	Specific entropy
ΔG°	_	Gibbs free energy

Α	_	Cell active area
С	_	Step of perturbation
D	_	Duty cycle
F	_	Faraday's constant
R	_	Universal gas constant
Т	_	Operational temperature
k	_	Number of discrete sampling steps
n	_	Number of electrons
t	_	Time

LIST OF ABBREVIATIONS

AFC	_	Alkaline Fuel Cell
DC	_	Direct Current
FLC	_	Fuzzy Logic Controller
IGBT	_	Insulated Gate Bipolar Transistor
INC	_	Incremental Conductance
MATLAB	_	Matrix Laboratory
MCFC	_	Molten Carbonate Fuel Cell
MPC	_	Model Predictive Control
MPP	_	Maximum Power Point
MPPT	_	Maximum Power Point Tracking
P&O	_	Perturb and Observe
PAFC	_	Phosphoric Acid Fuel Cell
PEMFC	_	Proton Exchange Membrane Fuel Cell
PID	_	Proportional Integral Derivative
PSO	_	Particle Swamp Optimisation
P-I	_	Power-Current
PV	_	Photovoltaic
PWM	_	Pulse Width Modulation
SOFC	_	Solid Oxide Fuel Cell
V-I	_	Voltage-Current

CHAPTER 1

INTRODUCTION

1.1 Background

The continuous consumption of non-renewable energy sources such as oil, coal, and gas upon the dependency of people's lives in this era of globalization has resulted in depletion of its sources. Apart from that, this action also resulted in serious environmental pollution and greenhouse effect. The enormous growth in energy consumption has forced the development of cost-effective renewable energy-based technologies to replace fossil-fuel-powered machinery in a numerous application. This is due to the fact that fossil fuels still meet a significant part of the energy demand [1]. Hence, the rise in energy demand has led to the increase in usage of fossil fuels which resulting in dwindling fossil fuel resources and higher fossil fuel prices. Furthermore, the negative environmental impact of fossil fuel combustion such as global warming has exacerbated the problem.

Nowadays, renewable energy has grown in popularity remarkably over the last century, and it continues to expand at a much faster pace than traditional energy sources like oil and coal [2]. Therefore, there is a pressing need to look for abundant and sustainable energy sources. Among all renewable energy sources, solar energy is described as one of the best alternatives that can be utilized. Recently, fuel cells have gained popularity as a potential renewable energy source due to their low environmental impact [3]. A fuel cell is a electrochemical device that generates electricity by combining hydrogen and oxygen with water and heat as a byproduct [4]. According to Karami et. al [5], fuel cells provide a number of advantages such as high in efficiency and reliability, noise-free, and environment friendly since the energy conversion undergo electrochemical process without combustion. In fuel cell system, unit cell is a core component that executes the electrochemical energy conversion. It consists of an electrolyte that is in contact with negative and positive electrodes namely anode and cathode respectively [6]. Fuel cells can be categorized into five major types in accordance with the electrolyte type used as shown in Table 1.1 [7].

Characteristic	Types of Fuel Cells							
	PEMFC	AFC	PAFC	MCFC	SOFC			
Operating temperature (°C)	40 - 80	65 — 220	200	650	600 — 1000			
Electrolyte	Polymer membrane	Immobilized KOH liquid	Immobilized H ₃ PO ₄ liquid	Immobilized molten carbonate	Perovskites (ceramics)			
Electrode	Carbon	Platinum	Carbon	Nickel and nickel oxide	Perovskite and perovskite/metal cermet			
Catalyst	Platinum	Platinum	Platinum	Electrode material	Electrode material			
Interconnect	Carbon or metal	Metal	Graphite	Stainless steel or nickel	Nickel, ceramic, or steel			
Charge carrier	H+	ОН−	H+	CO ₃ ²⁻	0 ^{2–}			
Cell component	Carbon based	Carbon based	Carbon based	Stainless based	Ceramic based			
Fuel cell compatibility	H ₂ , methanol	H ₂	H ₂	H ₂ , CH ₄	H ₂ , CH ₄ , CO			

Table 1.1:	Major	types	of fuel	cells	[6], [8]
------------	-------	-------	---------	-------	--------	----

Among these types of fuel cells, PEMFC which on the other hand is known as polymer electrolyte membrane [9], is said to be a promising power source contender due to its striking features such as high efficiency, clean utilization, lightweight, fast start-up, low operating temperature and high power density [9 - 11]. In addition, PEMFC is also the most prominent fuel cell that is widely used various application as stated in [11].

1.2 Problem Statement

Despite the fact that fuel cell is a green energy technology invention, the implementation cost of a fuel cell system is expensive when compared to other sources [12] due to design complexity of the system [13]. Nowadays, researchers are driven to develop an accurate model of the PEMFC because of its widespread use and its distinct advantages. As a result, the modelling of PEMFC system has become significantly crucial for better comprehension and development of high efficiency PEMFC system [14]. In spite of this, the mathematical modelling of PEMFC based on empirical equations has been widely used because of the nonlinearity, multivariate, and tightly coupled properties of PEMFC. Thus, the use of optimization methods is required due to the scarcity of data, the modelling complexity, and the large number of unknown parameters [15].

Apart from that, the output power of PEMFC is highly dependent on parameters such as temperature, membrane water content, oxygen partial pressure, and hydrogen partial pressure which resulting the fuel cell to exhibits non-linear output characteristic [16]. According to [17], the fuel cell polarization curve has one unique operating point to be tracked namely maximum power point (MPP). MPP is a point where the PEMFC will generate its full power [18]. However, the location of this MPP varies depending on the operating conditions [19]. Hence, a maximum power point tracking (MPPT) algorithm is used to monitor this MPP. A robust MPPT is essential to ensure maximum power extraction and energy utilization by the fuel cell at different operating conditions [20].

When it comes to developing an MPPT with fuel cells, there have been a plethora of approaches that have been published such as Perturb and Observe (P&O) [21], Incremental Conductance (INC) [22], Fuzzy Logic Control (FLC) [23], Particle Swarm Optimization (PSO) [24] and Model Predictive Control (MPC) [25]. However, these algorithms are different in terms of complexity, accuracy, and speed. Furthermore, some of the existing MPPT algorithm suffers high oscillation and slow convergence. Omar et. al [26] stated that each routine can be classified relative to the type of control variable that it employs, such as voltage, current, and duty cycle. Therefore, the proposed MPPT algorithm in this project will be compared with other existing algorithms in order to verify the trueness of their robustness on PEMFC efficiency.

1.3 Objectives

The objectives of this project are as follows:

- To develop a fully functional PEMFC based on the mathematical modelling in MATLAB/Simulink.
- To implement a predictive MPPT algorithm for the PEMFC.
- To compare predictive MPPT algorithm with other existing MPPT techniques on PEMFC's performances.

1.4 Project Scope

The aim of this project is to develop PEMFC system with predictive MPPT algorithm. This project involves research on the general concept of PEMFC and fundamentals of model predictive control. The development of the simulation model for this project is based on the parameters obtained from mathematical modelling of previous research. This project focuses on improving the performance of fully functional PEMFC from past studies by using predictive MPPT algorithm. Throughout this project, MATLAB/Simulink will be used to design the PEMFC with predictive MPPT control. Then, a simulation will be done by using MATLAB/Simulink to validate and execute the simulation model. The results obtained from the simulation will be used to examine and analyse the performance of PEMFC with predictive control under different operating conditions.

1.5 Thesis Outline

This project report is divided into five chapters, with an appendix including references and various attachments. The project is organized in the following order: introduction, literature review, methodology, results and discussion, and conclusion. The summary of each chapter is described as follows.

Chapter 1 (introduction) entails the background study of the proposed project, which is related to renewable energy and fuel cell. This chapter also includes the problem statement, objectives, and scope of the project.

Chapter 2 (literature review) explains the reviews and studies that have been done for better comprehension of proposed project. This chapter elucidates the working principle of PEMFC and its mathematical modelling. Apart from that, types of power electronics converters and MPPT algorithm are also covered in this chapter.

Chapter 3 (methodology) outlines the proposed methodology and succinct process that involved in the project accomplishment. Further details on the method and technique used for the proposed project are discussed in this chapter. This chapter also consists of project flowchart and simulation software that will be used throughout the project completion.

Chapter 4 (results and discussion) emphasizes on the further and detailed discussion regarding the simulation results and outcomes of the proposed project. This chapter also presents simulation graphs obtained from MATLAB/Simulink.

Chapter 5 (conclusion) summarizes the entire project and conclude the obtained results. This chapter also provides few recommendations for future improvements to overcome the limitations encountered throughout the project and boost the efficiency and performance of PEMFC.